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(54) A method and apparatus for combining a plurality of images without incurring a visible seam

(57) The present invention eliminates artifacts in an image formed using a plurality of imaging sources. Visible seams in the image are eliminated by randomizing the stitch point (18) between the scan lines (44, 46) produced by each imaging source. The randomization may be optimized by additionally applying a method for relocating the random stitch point (18) based on the data content of the scan line, adjacent scan lines, and other

criteria. The present invention further compensates for in-scan and cross-scan errors caused by thermally induced errors, spinner synchronization errors, mechanical misalignment, and other factors associated with the use of a plurality of imaging systems (30). A photodetector system (120, 122, 124), comprising a mask (124) having a pair of triangular openings (128, 128'), provides measurements of the in-scan and cross-scan errors.

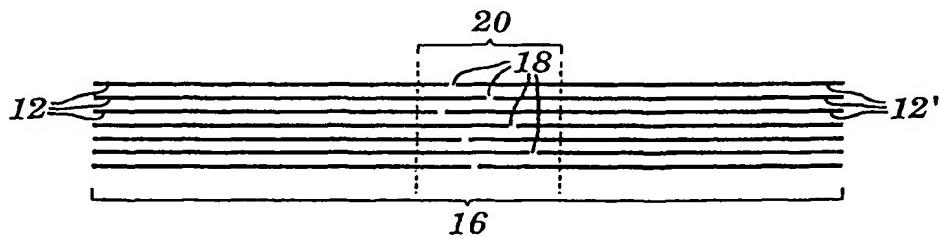


FIG. 2

Description**FIELD OF THE INVENTION**

[0001] The present invention is in the field of imaging systems. More particularly, the present invention provides a method and apparatus for combining ("stitching") a plurality of images produced by multiple imaging sources into a single image without creating a visible seam or other artifacts at the interfaces between the plurality of images.

BACKGROUND OF THE INVENTION

[0002] Flatfield scanning is commonly used in a number of applications, including flatbed scanners, capstan imagesetters, and even some external drum systems (e.g., large capstans). A serious limitation of many flatfield scanning systems is that there are practical limits to the length of the scan line. This generally limits the page width of these systems to the range of 14 to 18 inches. In an attempt to overcome this page width limitation, efforts have been made, with limited success, to combine the partial scan lines produced by a plurality of imaging sources into a single, composite image. Unfortunately, the seams between the partial scan lines produced by each imaging source are generally highly visible in the composite image. Additional artifacts produced by in-scan errors, cross-scan errors, pixel size variations, exposure variations, and other factors, may also be introduced, further diminishing the quality of the composite image. The in-scan and cross-scan errors may be produced for a number of reasons including spinner synchronization errors, thermally induced errors, or mechanical misalignment.

[0003] The present invention incorporates many unique features which eliminate these and other problems associated with the use of multiple imaging sources to create a single image.

SUMMARY OF THE INVENTION

[0004] The present invention provides various methods and apparatus for eliminating artifacts in an image formed using a plurality of imaging sources. For example, the present invention provides a unique stitching method for eliminating visible seams in the image by randomizing the stitch point between the scan lines produced by each imaging source. The randomization may be further optimized by additionally applying a method for relocating the random stitch point based on the data content of the scan line, adjacent scan lines, and other criteria.

[0005] The present invention also provides methods and apparatus for substantially eliminating in-scan and cross-scan errors caused by thermally induced errors, spinner synchronization errors, mechanical misalignment, and other factors associated with the use of a plu-

rality of imaging systems. A unique photodetector system, comprising a mask having a pair of triangular openings, provides measurements of the in-scan and cross-scan errors.

BRIEF DESCRIPTION OF THE DRAWINGS

[0006] The features of the present invention will best be understood from a detailed description of the invention and a preferred embodiment thereof selected for the purposes of illustration and shown in the accompanying drawings in which:

FIG. 1 shows the type of visible seam commonly produced between the scan lines generated by a pair of imaging sources in accordance with the prior art;

FIG. 2 illustrates the manner in which the location of the stitch point between each pair of scan lines is randomized within a stitch zone in accordance with the present invention to significantly reduce the visibility of stitching point errors;

FIG. 3 illustrates an imaging system incorporating a pair of imaging sources in accordance with the present invention;

FIG. 4 is provided to illustrate the "all white", "all black" and "zone boundary" algorithms for relocating a stitch point according to the present invention; FIG. 5 is a flowchart illustrating the "all white" algorithm for relocating a stitch point;

FIG. 6 is a block diagram of a system for reducing in-scan and cross-scan errors in accordance with the present invention;

FIGS. 7A-7C illustrate examples of thermally induced in-scan errors;

FIG. 8 illustrates a photodetector system for detecting in-scan and cross-scan errors;

FIG. 9 illustrates a mask including a pair of back to back 30-60-90 triangular openings for use in the photodetector system of FIG. 8;

FIG. 10 illustrates a technique, using the photodetector system of FIG. 8, for determining the relative locations of the imaging surface and the imaging sources;

FIGS. 11 and 12 illustrate an example of a cross-scan error that may occur in the imaging system of FIG. 3, and a method according to the present invention for compensating for the cross-scan error;

FIG. 13 illustrates a technique for determining cross-scan error according to the present invention;

FIG. 14 illustrates an imaging system incorporating a pair of oppositely directed imaging sources in accordance with an alternate embodiment of the present invention; and

FIG. 15 illustrates a scanning system incorporating a pair of image capture systems in accordance with the present invention.

DETAILED DESCRIPTION OF THE INVENTION

[0007] The features and advantages of the present invention are illustrated in detail in the accompanying drawings, wherein like reference numerals refer to like elements throughout the drawings.

[0008] In prior art imaging systems wherein a plurality of individual scan lines are combined to form a longer scan line, deleterious visible artifacts are often produced in the recorded image. In FIG. 1, for example, there is illustrated a highly visible seam 10 created when the partial scan lines 12, 12' produced by a pair of imaging sources are butted end to end in the same stitch location 14 to form a series of longer, composite scan lines 16. The seam 10 is visible, and highly noticeable, on the recorded image, unless near perfect alignment between the ends of the partial scan lines 12, 12' is achieved.

[0009] As illustrated in FIG. 2, the present invention eliminates the seam 10 by stitching each pair of the partial scan lines 12, 12' together at a random stitch point 18 within a stitch zone 20 having a predetermined width. Preferably, the predetermined width of the stitch zone 20 is chosen to be on the order of twenty (20) to several hundred pixels in width, although other widths may be used depending upon the type of imaging system, scanning resolution, and other factors.

[0010] Comparing FIG. 1 to FIG. 2, it can be easily seen that the random stitch points 18 depicted in FIG. 2 are much less visible than the aligned stitch points 14 of FIG. 1 which form the visible seam 10. Essentially, the seam between the partial scan lines 12, 12' in FIG. 2 is "blurred" due to the line by line randomization of the random stitch points 18.

[0011] A simplified diagram of an imaging system 30 incorporating a pair of imaging sources 32, 34 in accordance with the present invention is illustrated in FIG. 3. It should be clear, however, that the present invention may be applied to an imaging system comprising any number of individual imaging sources, without departing from the intended scope of the present invention as set forth in the claims. For example, the composite scan line produced by stitching a pair of partial scan lines together may additionally be stitched to a third partial scan line or another composite scan line to form an even longer scan line. Thus, the number of partial and/or composite scan lines which may be stitched together in accordance with the present invention is virtually unlimited.

[0012] The imaging system 30 includes a first, master imaging source 32, and a second, slave imaging source 34. The master imaging source 32 includes a modulated laser source 36 for producing an imaging beam 38M, a rotating deflector 40 for writing the imaging beam 38M across the imaging media 42 supported on an imaging surface 43 in a partial scan line 44 (master scan line), a spin motor 48M for rotating the deflector 40, and a master controller 50 for controlling the operation of the master imaging source 32. Similarly, the slave imaging source 34 includes a modulated laser source 36 for pro-

ducing an imaging beam 38S, a rotating deflector 40 for writing the imaging beam 38S across the imaging media 42 in a partial scan line 46 (slave scan line), a spin motor 48S for rotating the deflector 40, and a slave controller

5 52 for controlling the operation of the slave imaging source 34. Other types of writing sources, such as light emitting diodes (LED's), xerographic systems (e.g., toner based), ink-jet systems, or the like may also be used in accordance with the present invention to record the

10 master and slave scan lines 44, 46 on the imaging media 42. An imaging system controller 56 is provided to coordinate the operation of the master and slave imaging sources 32, 34. The imaging media 42 may be any type of recording media commonly imaged in a flatfield system, including web-type media, film, plates, and the like. Recording media for use with xerographic, ink-jet, or similar recording systems may also be used.

[0013] In this imaging system, the master and slave imaging sources 32, 34 remain stationary while the recording media 42 is displaced during imaging. A drive system 60 of a type known in the art is used to displace the recording media 42 past the master and slave imaging sources 32, 34 to produce a series of composite scan lines 16 (see FIG. 2), each formed by the combination

15 of a master scan line 44 and a slave scan line 46. A drive controller 62 is coupled to the imaging system controller 56 to synchronize media displacement and scan line imaging. Alternately, the imaging sources 32, 34 may be displaced during imaging while the recording

20 media 42 remains stationary.

[0014] In FIG. 3, the master imaging source 32 is configured to image the master scan line 44 from a start point 70 to a random end point 72 within the stitch zone 20. Similarly, the slave imaging source 34 is configured to image the slave scan line 46 from a random start point 74 in the stitch zone 20 to an end point 76. Together, the master scan line 44 and slave scan line 46 form a composite scan line 16 (FIG. 2). The stitch point 78 at which the master scan line 44 ends and the slave scan line 46

25 begins is randomly chosen from scan line to scan line

30 by the imaging system controller 56 in accordance with known randomizing algorithms. The present invention further provides additional optimizing algorithms (described below) which are used to relocate the original random stitch point based on factors such as the location of the stitch point in adjacent scan lines, the actual data content of the scan lines, and the type of artifacts which are to be minimized.

[0015] Several optimizing algorithms in accordance

35 with the present invention are described with reference to FIG. 4, which illustrates a pattern of pixels 80 in and around the stitch zone 20. For convenience, the rows (i.e., scan lines) are identified by numbers and the columns are identified by letters. These algorithms include

40 "all white", "all black", and "zone boundary" types. The examples described below are limited to the establishment of a stitch point in row #2. However, it should be clear that these randomizing algorithms are applied in

a line-by-line manner to all scan lines of the image.

[0016] In the following example, it is assumed that the random stitch point for row #2 is initially randomly chosen to be at the location between pixels "P" and "R." As seen in FIG. 4, this location falls between two black pixels. If the "all white" algorithm is being used, the algorithm determines if an alternate "all white" location (i.e., between two white pixels) is available in the stitch zone 20 within a predetermined number of pixels from the original random stitch point. If the predetermined number of pixels is chosen, for example, to be less than or equal to ten (10), then the location in row #2 between pixels "U" and "V" meets this criteria, and the stitch point is moved to that location. If an "all white" location is not available within the predetermined number of pixels from the original random stitch point, then the original random stitch point is retained.

[0017] Contrastingly, if an "all black" algorithm were being used in this example, the original random stitch point would be satisfactory, and would not be relocated, since it is already located between the two black pixels at "P" and "R." However, if the original random location of the stitch point did not fall between two black pixels, the "all black" algorithm would determine if an alternate "all black" location is available in the stitch zone 20 within a predetermined number of pixels from the original random stitch point. If such a location is available, then the stitch point is relocated to that position in the row. However, if an "all black" location is not available within the predetermined number of pixels from the original random stitch point, then the original random stitch point is retained.

[0018] Finally, if the "zone boundary" algorithm were being used in this example, the original random stitch point between the pixels at locations "P" and "R" would not be satisfactory, since it does not fall between the transition of a black pixel and a white pixel. The "zone boundary" algorithm subsequently determines if an alternate "zone boundary" location is available in the stitch zone within a predetermined number of pixels from the original random stitch point. If the predetermined number of pixels is again chosen to be less than or equal to ten (10), then the location in row #2 between the black and white pixels located at the "T" and "U" positions, respectively, meets this criteria, and the stitch point is relocated to that position in the row. If a "zone boundary" location is not available within the predetermined number of pixels from the original random stitch point, then the original random stitch point is retained.

[0019] A summary of the "all white" algorithm is illustrated in flowchart form in FIG. 5. Similar flowcharts can be used to describe the flow of the "all black" and "zone boundary" algorithms described above.

[0020] In block 150, a random stitch point is generated for the first row indicating the location in the stitch zone 20 where the master and slave scan lines 44, 46 are to be joined. If the randomly chosen stitch point falls between two white pixels 152, the stitch point is retained

154. If the randomly chosen stitch point does not fall between two white pixels 152, processing continues with block 156, which determines whether an alternate "all white" location for the stitch point is available within the

5 stitch zone. If not, the original stitch point is retained 154. If an alternate "all white" location is available within the stitch zone, the algorithm determines 158 whether the alternate location falls within N-pixels from the original location of the stitch point. The value of N is controlled 10 in block 160. If the alternate location is outside the N-pixel value, the original stitch point is retained 154. If acceptable 158, the alternate location is used 162 in lieu of the original stitch point. Processing subsequently continues for each remaining row 164, 166 of the image.

15 [0021] Two dimensional randomizing algorithms similar to the one dimensional algorithms described above may also be employed. The two dimensional algorithms take into account not only the data within the row currently under consideration, but also the data within one 20 or more adjacent rows. Again, several algorithms may be used, including "all white", "all black", and "zone boundary." An example of the two dimensional "all white" algorithm is presented below.

[0022] Assume for example that the original random 25 stitch point falls between pixels "P" and "R" in row #8 of FIG. 4. Although this stitch point would satisfy the one-dimensional "all white" algorithm described above, it fails to meet the criteria of an "all white" algorithm in two dimensions, since the corresponding locations between pixels "P" and "R" in rows #7 and #9 fall between black 30 pixels. As in the one dimensional algorithm, a search is made in row #8 (within the stitch zone) for an alternate "all white" location, within a predetermined number of pixels from the original random stitch point, that best satisfies 35 the two-dimensional "all white" requirement. For a pixel range of less than or equal to ten (10), for example, the best location for the stitch point falls between the white pixels at locations "V" and "W." As in the one dimensional case, the original stitch point is retained if 40 a better "all white" location is not available within the predetermined pixel range.

[0023] Three dimensional algorithms follow the previously described one and two dimensional constructions except that three dimensions of data are analyzed. For 45 example, in color printing applications, the data for each color is contained of a separate film master or printing plate. For three dimension correction the algorithm considers data in two dimensions as previously described, but with further constraints on the data in the other color 50 layers (e.g., separations) of the image.

[0024] Although the use of random stitch points will minimize the visibility of stitch point errors, additional corrections may be required due to other factors. For 55 example, errors along the scan line, herein referred to as in-scan errors, such as gaps or overlaps, may occur at or adjacent the stitch point due to spinner synchronization errors, thermally induced variations, mechanical misalignment, and other factors.

[0025] To reduce spinner synchronization errors, the spin motors 48M, 48S of the master and slave imaging sources 32, 34, are synchronized to the same reference clock 90 as illustrated in FIG. 6. The rotational speed of the master spin motor 48M, provided by a corresponding encoder, is fed back to the input of the master spin motor through a control loop 92. Similarly, the rotational speed of the slave spin motor 48S, again provided by an encoder, is fed back to the input of the slave spin motor 48S through a control loop 94. The control loops 92, 94 are configured to monitor the speed of each respective spin motor, and to adjust the speed, as necessary, to ensure that the motors are each rotating at the fixed rate required for imaging.

[0026] The speed of the master spin motor 48M is additionally provided to the master pixel clock 96 through a phase locked loop (PLL) 98. In a similar manner, the speed of the slave spin motor 48S is provided to the slave pixel clock 100 through a PLL 102. The output of the master and slave pixel clocks 96, 100 are provided to the modulated laser sources 36 of the master and slave imaging sources 32, 34 to control the pixel data recording rate in the master and slave scan lines 44, 46. In this manner, time varying positional errors of the spin motors 48M, 48S, caused by load torque variations in each motor and other factors, are individually corrected by the corresponding PLL 98, 102 thereby ensuring an even spacing of recorded dots on the imaging media 42.

[0027] Imaging errors in both the in-scan and cross-scan directions may occur, for example, in response to the expansion, contraction, or misalignment of the structure mounting the master and slave imaging sources 32, 34 relative to the imaging surface 43. Further, although the imaging sources 32, 34 are preferably mounted to a common support structure (not shown), such imaging errors generally do not affect the master and slave imaging sources 32, 34 identically.

[0028] Examples of in-scan errors are illustrated with reference to FIG. 7A, 7B, and 7C. Under ideal conditions, the imaging beams 38M, 38S of the master and slave imaging sources 32, 34 meet at the random stitch point 18 as shown in FIG. 7A. As the master and slave imaging sources 32, 34 move closer to the imaging surface 43, the imaging beams 38M, 38S no longer meet at the stitch point 18, and a gap 110 is formed between the master and slave scan lines. Contrastingly, as the imaging sources 32, 34 move away from the imaging surface 43, the master and slave imaging beams 38M, 38S intersect prior to reaching the imaging surface, effectively forming an overlap 112 between the master and slave scan lines. These types of errors occur, in part, because the master and slave imaging beams 38M, 38S are not telecentric.

[0029] As detailed below, the present invention compensates for these and other types of errors using a unique photodetector-based system.

[0030] The measurement and correction of imaging errors is carried out using a photodetector system in-

cluding a pair of photodetectors 120, 122, and a mask 124. As shown in FIG. 8, the photodetectors 120, 122 are located in the image plane at one end of the imaging surface 43, outside the scanning area of the imaging system. Preferably, the photodetectors 120, 122 are recessed into the imaging surface, and a suitably shaped recess 126 is provided for the mask 124 such that the mask surface is virtually coplanar to the imaging surface 43. A single photodetector may also be used in lieu of the pair of photodetectors 120, 122.

[0031] The mask 124 is illustrated in greater detail in FIG. 9. In the preferred embodiment of the present invention, the mask 124 includes a pair of back to back 30-60-90 triangular openings 128, 128', spaced apart a predetermined distance D corresponding to the width of the stitch zone 20, formed in an opaque support 130. The angles of the triangular openings 128, 128' may vary, however, based on the specific resolution of the imaging sources 32, 34 and other factors. Preferably, the mask is formed of glass which is coated with an opaque material such as chromium. The coated glass has two uncoated areas which form two transparent triangles. When the mask 124 is positioned within the recess 126, the triangular openings 128, 128' are configured to lie directly above the photodetectors 120, 122.

[0032] To compensate for in-scan errors such as gaps and overlaps, and to ensure accurate butting of the master and slave scan lines 44, 46 at the stitch point 18 of each composite scan line 16, the relative in-scan position of the master and slave imaging beams 38M, 38S can be regulated using information provided by the photodetectors 120, 122.

[0033] First, the master imaging beam 38M is scanned across the pair of triangular openings 128, 128' to determine the time it takes the beam 38M to pass from one end of the stitch zone 20, corresponding to the vertical edge 132 of the triangular opening 128, to the other end of the stitch zone 20, corresponding to the vertical edge 134 of the triangular opening 128'. As the master imaging beam 38M passes over the triangular openings 128, 128', it creates a pulse on each of the photodetectors 120, 122. The time required to pass from the vertical edge 132 of the triangular opening 128 to the vertical edge 134 of the triangular opening 128' corresponds to the time between the end of the pulse detected by the photodetector 120 and the beginning of the pulse detected by photodetector 122.

[0034] Under ideal conditions, as illustrated in FIG. 10, since the angular velocity of the master spin motor 48M and the distance D between the vertical edges 132, 134 of the triangular openings 128, 128' are known, the master spin motor 48M should spin through an angle A in a time T as the master imaging beam 38M traverses the distance D. If, however, the imaging surface 43 moves closer to the master imaging source 32 as shown in FIG. 10, the time T' required to traverse the distance D between the vertical edges 132, 134 of the triangular openings 128, 128', as determined by the photodetec-

tors 120, 122, increases, since the master spin motor 48M must spin through a larger angle A' (at the same angular velocity) to traverse the same distance D. Analogously, if the imaging surface 43" moves away from the master imaging source 32, the time T" required to traverse the distance D, as measured by the photodetectors, deceases, since the master spin motor 48M must spin through a smaller angle A" to traverse the distance D.

[0035] A similar process is carried out using the slave imaging beam 38S to determine if the imaging surface 43 has moved relative to the slave imaging source 34.

[0036] By comparing the detected beam traversal times of the master and slave imaging beams 38M, 38S to an expected value, the imaging system 30 can substantially eliminate thermally induced in-scan errors such as gaps 110 and overlaps 112 between the master and scan lines 44, 46. As illustrated in FIG. 6, a master beginning of line (BOL) shift and line length correction module 140 and a slave BOL shift and line length correction module 142 are provided to compensate for thermally induced in-scan errors in the master and slave scan lines 44, 46, respectively. Each of the modules 140, 142 receives beam information from a beam position detector 146 which acquires and analyzes the output from the photodetectors 120, 122. The output from each module 140, 142 is provided to a respective one of the PLL's 98, 102 to control the operation of the master and slave pixel clocks 96, 100.

[0037] In the case where the imaging surface 43' moves closer to the master and slave imaging sources 32, 34, the length of the master and slave scan lines 44, 46 must be effectively "stretched" in time such that the correct number of pixels are imaged across a distance D in a nominal time T. This is achieved, for example, by imaging fewer pixels for each encoder count of the master and slave motors 48M, 48S, and by imaging through a greater number of encoder counts (i.e., through a larger angle A'). In addition, the BOL of the master and slave scan lines 44, 46 must be shifted in position such that imaging ends (master) or starts (slave) at the stitch point 18, thereby eliminating the gap 110.

[0038] In the analogous case where the imaging surface 43" moves further away from the master and slave imaging sources 32, 34, the length of the master and slave scan lines 44, 46 must be effectively "compressed" in time to eliminate the overlap 112. This may be achieved, for example, by imaging a greater number of pixels for each encoder count of the master and slave motors 48M, 48S, and by imaging through fewer encoder counts (i.e., a smaller angle A"). Again, the BOL of the master and slave scan lines 44, 46 must be adjusted accordingly to ensure that imaging ends (master) or starts (slave) at the stitch point 18, thereby eliminating the overlap 112.

[0039] In the case where the imaging surface 43 moves closer to the master imaging source 32 and further away from the slave imaging source 34 (or vice ver-

sa), a combination of the above techniques is applied to eliminate any gap or overlap at the stitch point 18.

[0040] The photodetectors 120, 122 and mask 124 can also be used to compensate for cross-scan error between the master and slave scan lines 44, 46. As with in-scan errors there can be several sources of cross-scan error, including, for example, velocity variations during the scan, and mechanical misalignment of the master and/or slave imaging sources 32, 34.

5 [0041] An example of a cross-scan error 170 between the master and slave scan lines 44, 46 is illustrated in FIG. 11. This error can be expressed in terms of line widths of the imaging addressability of the imaging sources 32, 34. In this example, a cross-scan error of 15 2.45 line widths exists between the master scan line 44 and the slave scan line 46.

[0042] To compensate for this cross-scan error, given a media transport motion in the direction of arrow 172, the imaging of the master scan line 44 must be delayed 20 by 2.45 line widths. In accordance with the present invention, this can be accomplished in two steps.

[0043] First, to compensate for the integer portion of 25 the cross scan error (2, in the current example), the imaging data for the master scan line 44 and the two following master scan lines 44', 44" (FIG. 12) is buffered prior to being imaged by the master imaging source 32. This prevents the master scan lines 44, 44', 44" from being imaged prior to the imaging of the lagging slave scan line 46. To compensate for the fractional portion of 30 the cross scan error (0.45, in the current example), a rotational offset 174 (FIG. 6) of 0.45 line widths is applied to master motor 48M, such that the start of imaging of the master scan line 44 is further delayed by 0.45 line widths relative to the start of imaging of the slave scan 35 line 46. The master scan line 44 is subsequently accessed from the buffer and recorded on the imaging media, and the process is repeated as necessary. Of course, it should be clear that the converse of the above-described method may be used in the case where the 40 master scan line 44 lags the slave scan line 46.

[0044] The degree of cross-scan error is measured by determining the difference in time required for the master and slave imaging beams 38M, 38S to pass across the triangular openings 128, 128', respectively, of the 45 photodetector system. Specifically, as illustrated in FIG. 13, the master imaging beam 38M is passed over the triangular opening 128 as indicated by A, and the time required to pass from the hypotenuse H of the opening 128 to the vertical edge 132 thereof is detected by the underlying photodetector 120. Similarly, the slave imaging beam 38S is passed over the triangular opening 128' as indicated by B, and the time required to pass from the vertical edge 134 to the hypotenuse H' of the opening 128' is detected by the photodetector 122. Since the 50 size of the triangular opening 128 is known, and the angular velocity of the master spin motor 48M is known and constant, the point of intersection of the master imaging beam 38M on the vertical edge 132 of the trian-

gular opening 128 can be easily determined. The same applies to the intersection point of the slave imaging beam 38S on the vertical edge 134 of the triangular opening 128'. These values can then be compared to quantify the cross-scan error E.

[0045] In an alternated embodiment, a mask including a single triangular opening is used to measure the cross-scan error. In this embodiment, a single photodetector may be used. The cross-scan error is measured by sequentially imaging the master and slave imaging beams 38M, 38S over the triangular opening in the mask, and by comparing the time required for the imaging beams 38M, 38S to travel between the hypotenuse and vertical edge of the triangular opening.

[0046] In other embodiments of the present invention, the in-scan and cross-scan error may be measured using a mask having other types of openings therethrough. For example, the mask may include a triangular opening and a vertical slit, one or more angled and vertical slits, a combination of triangular openings and vertical/angled slits, or other suitably shaped openings. The in-scan error may be determined, for example, by measuring the time required for an imaging beam to pass from the vertical edge of a triangular opening to a vertical slit, or vice versa, or from one vertical slit to another vertical slit. Analogously, the cross-scan error may be determined by comparing the time required for the master and slave imaging beams to travel between an angled and a vertical slit or vice versa.

[0047] A further feature of the present invention is illustrated in FIG. 14, wherein a pair of imaging sources 180, 182, which are configured to scan imaging beams 184, 186 in opposite directions, are used to image a composite scan line 188 formed of partial scan lines 190, 192. This configuration eliminates several error sources present in the imaging system previously described with regard to FIG. 3.

[0048] When using the oppositely scanning imaging sources 180, 182, the BOL 194, 196 of the partial scan lines 190, 192 are located in the center of the image, or elsewhere within the stitch zone 20 if a random stitch point is used. Advantageously, since the partial scan lines 190, 192 begin at substantially the same location, the gap/overlap errors which may occur due to uncompensated velocity variations or thermal variations during the scan are eliminated. Small line length errors may still occur, but these errors will not produce highly noticeable artifacts in the final image.

[0049] The use of the oppositely directed imaging sources 180, 182 also reduces cross-scan error as synchronization is established at the start of scan and any velocity variations which affect the cross-scan position of the beams due to the motion of the imaging surface in the cross-scan direction accumulate along the scan line and become an error in the line to line cross-scan spacing. This error is no more than already exists when using a single imaging system.

[0050] Although described above with regard to an

imaging system incorporating a plurality of imaging sources, it should be noted that many aspects of the present invention may be used in a scanning system wherein a plurality of image capture systems, each including a linear array of photosensitive elements or the like (e.g., a linear charge coupled device (CCD) array), are used to capture and convert an image into partial scan lines of digital data. Such a scanning system is illustrated in FIG. 15, wherein a pair of image capture systems 200, 202, each including a respective linear CCD array 204, 206, are used to capture partial scan lines 208, 210 of an image 212. The digital data for the partial scan lines may be stitched together at random locations within a stitch zone as previously described herein to form composite scan lines. The random stitching of the present invention may also be used to form composite scan lines based on the partial scan lines produced by the image capture system of an X-Y scanning system.

[0051] The foregoing description of the present invention has been presented for purposes of illustration and description. It is not intended to be exhaustive or to limit the invention to the precise form disclosed, and many modifications and variations are possible in light of the above teaching. Such modifications and variations that may be apparent to a person skilled in the art are intended to be included within the scope of this invention as defined by the accompanying claims.

30 Claims

1. An apparatus for compensating for errors in an imaging system (30), the apparatus characterised by:
- 35 a system for detecting errors in the imaging system (30), the error detecting system including a photodetector system (120, 122, 124), a mask (124) positionable over the photodetector system (120, 122, 124), and at least one opening (128, 128') in the mask (124); and a system for compensating for the detected errors.
- 40 2. The apparatus according to claim 1, wherein the mask (124) includes at least one triangular opening (128, 128') having interior angles of 30, 60, and 90 degrees.
- 45 3. The apparatus according to claim 1, wherein the mask (124) includes a pair of openings (128, 128') each including a vertical edge (132, 134), and wherein the vertical edges (132, 134) of the openings (128, 128') are separated by a distance D.
- 50 4. The apparatus according to claim 3, wherein the imaging system is characterised by:
first and second imaging sources (32, 34) for producing first and second imaging beams (38M,

- 38S), respectively, and for scanning the first and second imaging beams (38M, 38S) across an imaging surface (42) to produce first and second scan lines (44, 46), respectively, the first and second scan lines (44, 46) forming a composite scan line (16). 5
5. The apparatus according to claim 4, further characterised wherein the first and second imaging sources scan the first and second imaging beams (38M, 38S), respectively, across the pair of openings (128, 128') in the mask (124), and wherein the photodetector system (120, 122, 124) determines the time required for the first and second imaging beams (38M, 38S) to traverse the distance D. 10
6. The apparatus according to claim 5, further characterised wherein the error detecting system detects an in-scan error in the composite scan line (16) formed by the first and second scan lines (44, 46), based on the time required for the first and second imaging beams (38M, 38S) to traverse the distance D, and wherein the compensating system compensates for the detected in-scan error. 15
7. The apparatus according to claim 6, further characterised wherein the in-scan error includes a gap (110) between, or an overlap of, the first and second scan lines (44, 46). 20
8. The apparatus according to claim 6, further characterised wherein the compensating system compensates for the detected in-scan error by adjusting a length of at least one of the first and second scan lines (44, 46). 25
9. The apparatus according to claim 6, further characterised wherein the compensating system compensates for the detected in-scan error by adjusting a beginning of line of at least one of the first and second scan lines (44, 46). 30
10. The apparatus according to claim 1, wherein the imaging system includes an imaging source for producing an imaging beam and for scanning the imaging beam across an imaging surface (42) to produce a scan line. 35
11. The apparatus according to claim 10, further characterised wherein the imaging source scans the imaging beam across a pair of the openings (128, 128') in the mask (124), and wherein the error detecting system detects a displacement between the imaging source and the imaging system (30) by determining the time required for the imaging beam to traverse a distance D between the pair of openings (128, 128'). 40
12. The apparatus according to claim 1, wherein the imaging system (30) is characterised by: first and second imaging sources (32, 34) for producing first and second imaging beams (38M, 38S), respectively, and for scanning the first and second imaging beams (38M, 38S) across an imaging surface (42) to produce first and second scan lines (44, 46), respectively, the first and second scan lines (44, 46) forming a composite scan line (16). 45
13. The apparatus according to claim 12, wherein the mask (124) includes a plurality of triangular openings (128, 128'). 50
14. The apparatus according to claim 12, wherein the mask (124) includes at least one opening (128, 128') having a vertical portion, and at least one opening (128, 128') having an angled portion. 55
15. The apparatus according to claim 14, further characterised wherein the first and second imaging sources scan the first and second imaging beams (38M, 38S), respectively, across at least one of the openings (128, 128') in the mask (124), and wherein the photodetector system (120, 122, 124) determines the time required for the first and second imaging beams (38M, 38S) to travel between the vertical and angled portions of the at least one opening (128, 128') in the mask (124). 60
16. The apparatus according to claim 15, further characterised by a system for detecting a cross-scan error between the first and second scan lines (44, 46), based on the time required for the first and second imaging beams (38M, 38S) to travel between the vertical and angled portions of the at least one opening (128, 128') in the mask (124). 65
17. The apparatus according to claim 16, further characterised by a system for compensating for the cross-scan error. 70
18. The apparatus according to claim 17, wherein the compensating system is characterised by a system for realigning the first and second scan lines (44, 46). 75
19. The apparatus according to claim 18, wherein the realigning system is characterised by delaying the imaging of a leading one of the first and second scan lines (44, 46) until a lagging one of the first and second scan lines (44, 46) is being imaged. 80
20. A method for compensating for errors in an imaging system, characterised by: 85

providing a mask (124) having a pair of open-

- ings (128,128') therein separated by a distance D;
scanning first and second imaging beams (38M, 38S) over the mask (124);
detecting errors in the imaging system (30) by measuring the time required for the first and second imaging beams (38M, 38S) to traverse the distance D between the pair of openings (128,128'); and
compensating for the detected errors.
21. The method according to claim 20, further characterised by determining an in-scan error by comparing the time required for the first and second imaging beams (38M, 38S) to traverse the distance D to predetermined values.
22. The method according to claim 21, wherein the compensating step is further characterised by compensating for the in-scan error.
23. The method according to claim 22, wherein the step of compensating for the in-scan error is further characterised by adjusting a length of at least one of a first and a second scan line produced by the first and second imaging beams (38M, 38S), respectively.
24. The method according to claim 22, wherein the step of compensating for the in-scan error is further characterised by adjusting a beginning of line of at least one of a first and a second scan line produced by the first and second imaging beams (38M, 38S), respectively.
25. A method for measuring errors in an imaging system (30), the method characterised by:
providing a mask (124) including at least one opening (128,128') having a vertical portion, and at least one opening (128,128') having an angled portion;
scanning first and second imaging beams (38M, 38S) over the mask (124);
detecting errors in the imaging system (30) by measuring the time required for the first and second imaging beams (38M, 38S) to travel between the vertical and angled portions of at least one of the openings (128,128') in the mask (124); and
compensating for the detected errors.
26. The method according to claim 25, wherein the detecting step is further characterised by determining a cross-scan error by measuring the time required for the first and second imaging beams (38M, 38S) to travel between the vertical and angled portions of at least one of the openings (128,128') in the mask (124).
27. The method according to claim 26, wherein the compensating step is further characterised by compensating for the cross-scan error.
28. The method according to claim 27, wherein the step of compensating for the cross-scan error is further characterised by realigning a first scan line produced by the first imaging beam with a second scan line produced by the second imaging beam.
29. The method according to claim 28, wherein the realigning step is further characterised by delaying the imaging of a leading one of the first and second scan lines (44, 46) until a lagging one of the first and second scan lines (44, 46) is being imaged.
30. An imaging system (30) characterised by:
first and second imaging sources (32, 34) for producing first and second imaging beams (38M, 38S), respectively, and for scanning the first and second imaging beams (38M, 38S) across an imaging surface (42) to produce first and second scan lines (44, 46), respectively, thereby forming a composite scan line (16);
a system for displacing the imaging surface (42) or the first and second imaging sources (32, 34) to produce a series of the composite scan lines (16);
a system for detecting an in-scan error in each of the composite scan lines (16); and
a system for compensating for the detected in-scan error, the compensating system including a system for adjusting a length of at least one of the first and second scan lines (44, 46), and a system for adjusting a beginning of line of at least one of the first and second scan lines (44, 46).
31. The imaging system (30) according to claim 30, further characterised wherein the in-scan error include a gap (110) between, or an overlap of, the first and second scan lines (44, 46).
32. The imaging system (30) according to claim 30, further characterised wherein the system for detecting the in-scan error in each of the composite scan lines (16) is characterised by:
a photodetector system (120, 122, 124);
a mask (124) configured to be positioned over the photodetector system (120, 122, 124); and
at least one opening (128,128') in the mask (124).
33. The imaging system (30) according to claim 32, fur-

- ther characterised wherein at least two of the openings (128,128') in the mask (124) include a vertical edge (132, 134), and wherein the vertical edges (132, 134) of the openings (128,128') are separated by a distance D.

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34. The imaging system (30) according to claim 33, further characterised wherein the photodetector system (120, 122, 124) determines the time required for the first and second imaging beams (38M, 38S) to traverse the distance D.

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35. The imaging system (30) according to claim 34, further characterised wherein the in-scan error is determined by the detecting system by comparing the time required for the first and second imaging beams (38M, 38S) to traverse the distance D to pre-determined values.

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36. An imaging system (30) characterised by:

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first and second imaging sources (32, 34) for producing first and second imaging beams (38M, 38S), respectively, and for scanning the first and second imaging beams (38M, 38S) across an imaging surface (42) to produce first and second scan lines (44, 46), respectively, thereby forming a composite scan line (16); a system for displacing the imaging surface (42) or the first and second imaging sources (32, 34) to produce a series of the composite scan lines (16); a system for detecting cross-scan error in each of the composite scan lines (16); and a system for compensating for the detected cross-scan error, the compensating system including a system for delaying the imaging of a leading one of the first and second scan lines (44, 46) until a lagging one of first and second scan lines (44, 46) is being imaged.

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37. The imaging system (30) according to claim 36, wherein the system for detecting the cross-scan error in each of the composite scan lines (16) is characterised by:

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a photodetector system (120, 122, 124); and a mask (124) configured to be positioned over the photodetector system (120, 122, 124), the mask (124) including at least one opening (128,128') having a vertical portion, and at least one opening (128,128') having an angled portion.

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38. The imaging system (30) according to claim 37, further characterised wherein the first and second imaging sources (32, 34) scan the first and second imaging beams (38M, 38S), respectively, across the

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mask (124), and wherein the cross-scan error detecting system detects the cross-scan error by measuring and comparing the time required for the first and second imaging beams (38M, 38S) to travel between the vertical and angled portions of at least one of the openings (128,128') in the mask (124).

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39. An imaging system (30) characterised by:

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first and second imaging sources (32, 34) for producing first and second imaging beams (38M, 38S), respectively, and for scanning the first and second imaging beams (38M, 38S) across an imaging surface (42) in opposite directions to produce first and second scan lines (44, 46), respectively, thereby forming a composite scan line (16); a system for displacing the imaging surface (42) or the first and second imaging sources (32, 34) to produce a series of the composite scan lines (16).

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40. The imaging system (30) according to claim 39, further characterised wherein the first and second scan lines (44, 46) begin at substantially the same location on the imaging surface (42).

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41. A method for forming a composite scan line (16), the method characterised by:

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42. The imaging method according to claim 41, further characterised by:

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initiating the scanning of the first and second scan lines (44, 46) at substantially the same location on the imaging surface (42).

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43. An imaging system (30) characterised by:

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first and second imaging sources (32, 34) for producing first and second imaging beams (38M, 38S), respectively, and for scanning the first and second imaging beams (38M, 38S) across an imaging surface (42) in opposite directions to produce first and second scan lines (44, 46), respectively, thereby forming a composite scan line (16); a system for detecting a cross-scan error in the

composite scan line (16); and
a system for compensating for the detected
cross-scan error, the cross-scan error compen-
sating system including a system for delaying
the imaging of a leading one of the first and sec-
ond scan lines (44, 46) until a lagging one of
the first and second scan lines (44, 46) is being
imaged.

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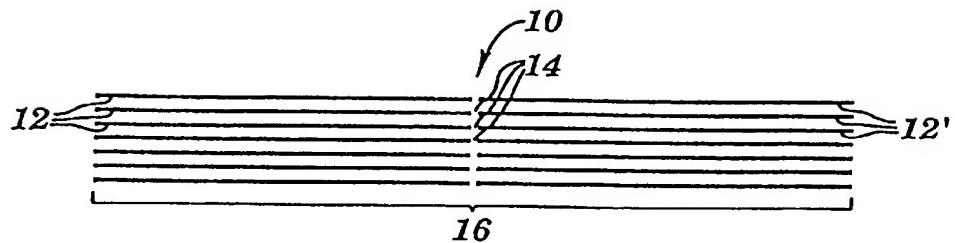


FIG. 1
PRIOR ART

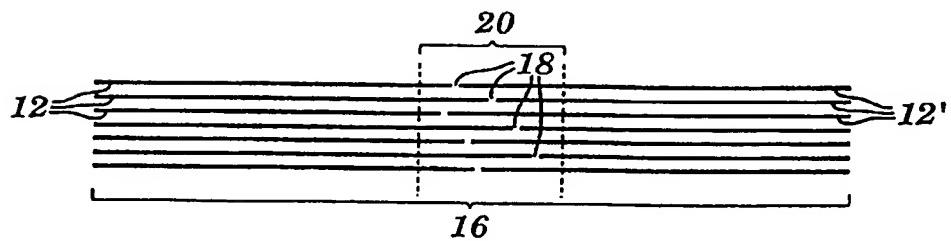


FIG. 2

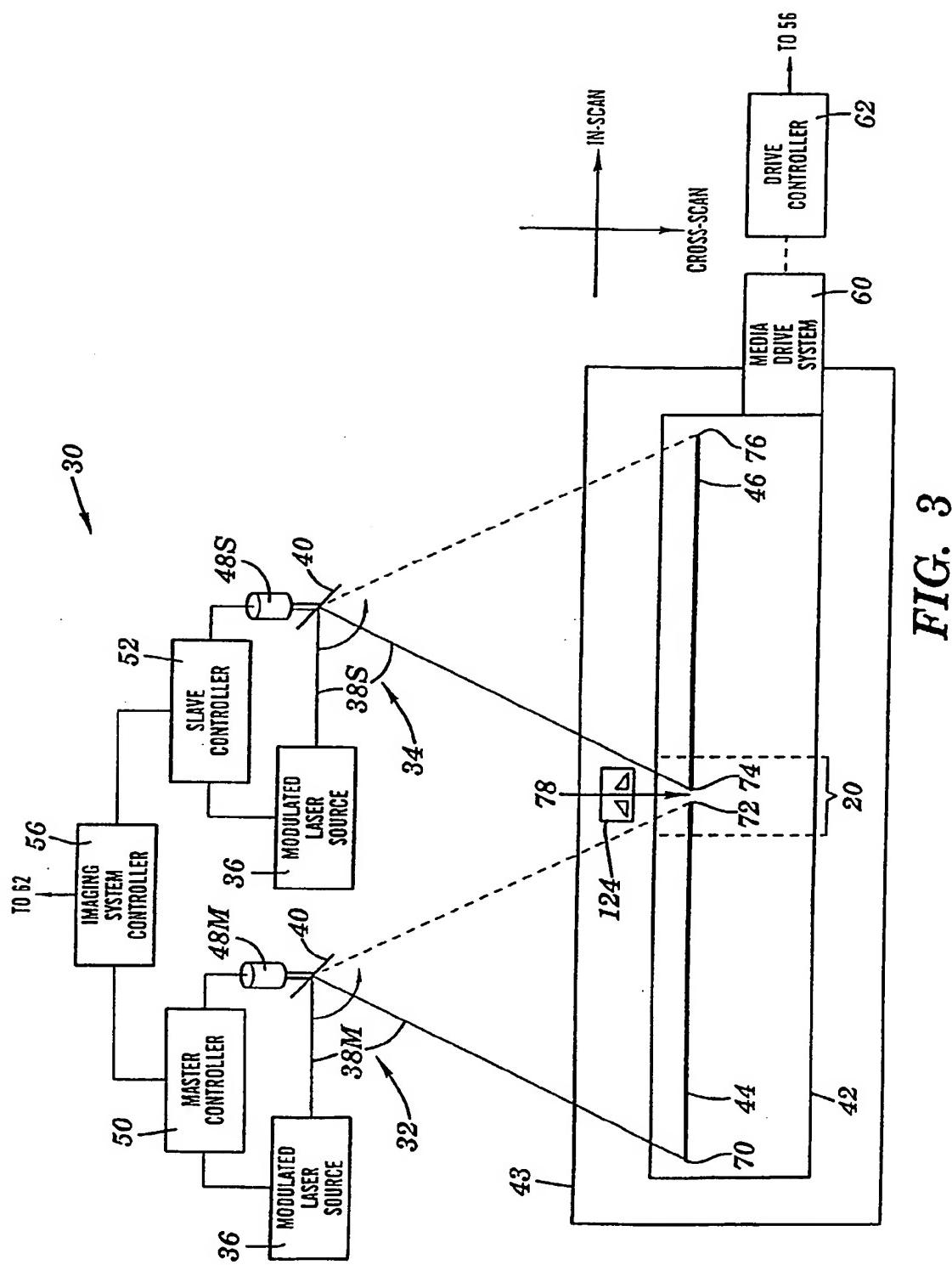


FIG. 3

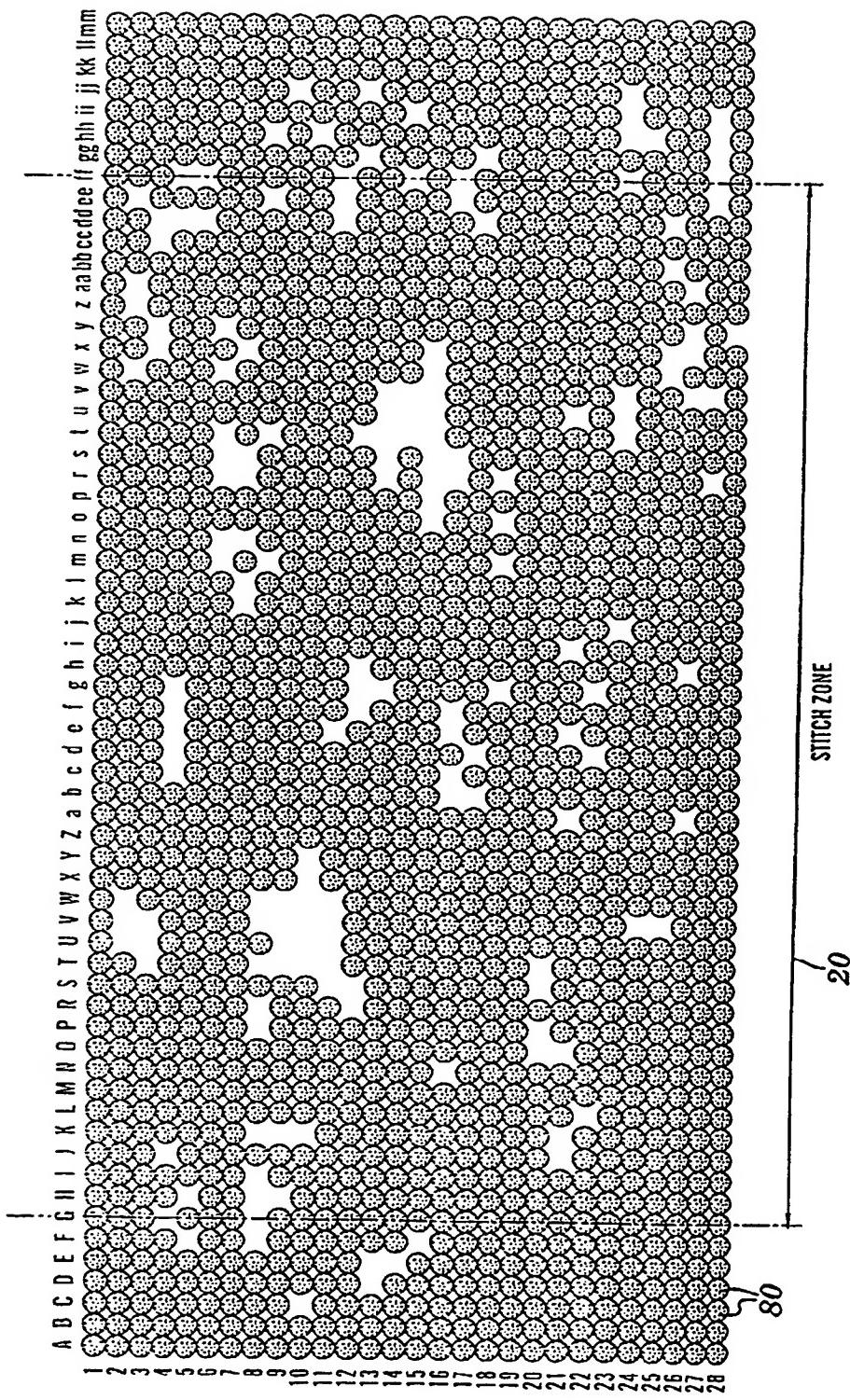
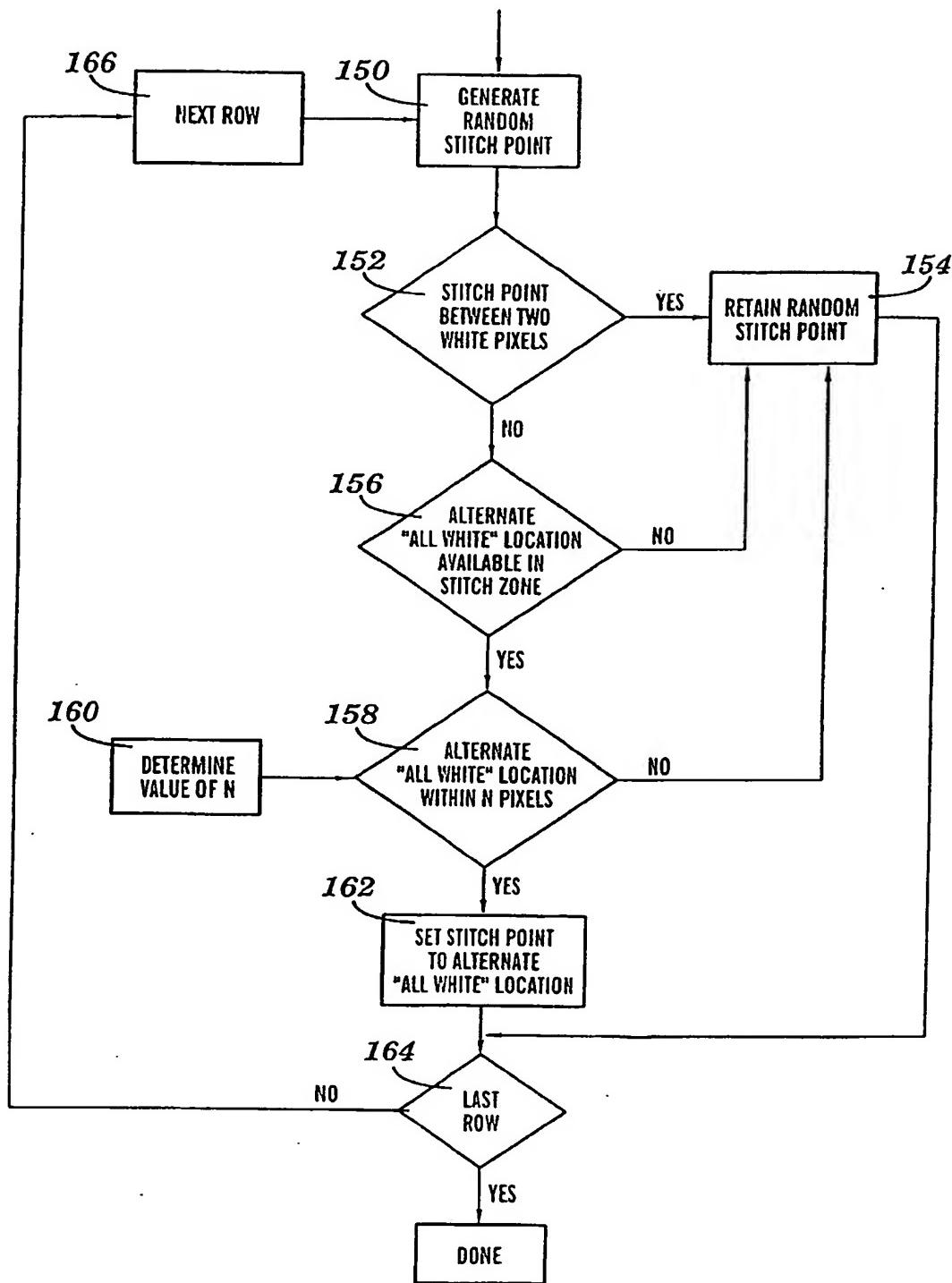


FIG. 4

***FIG. 5***

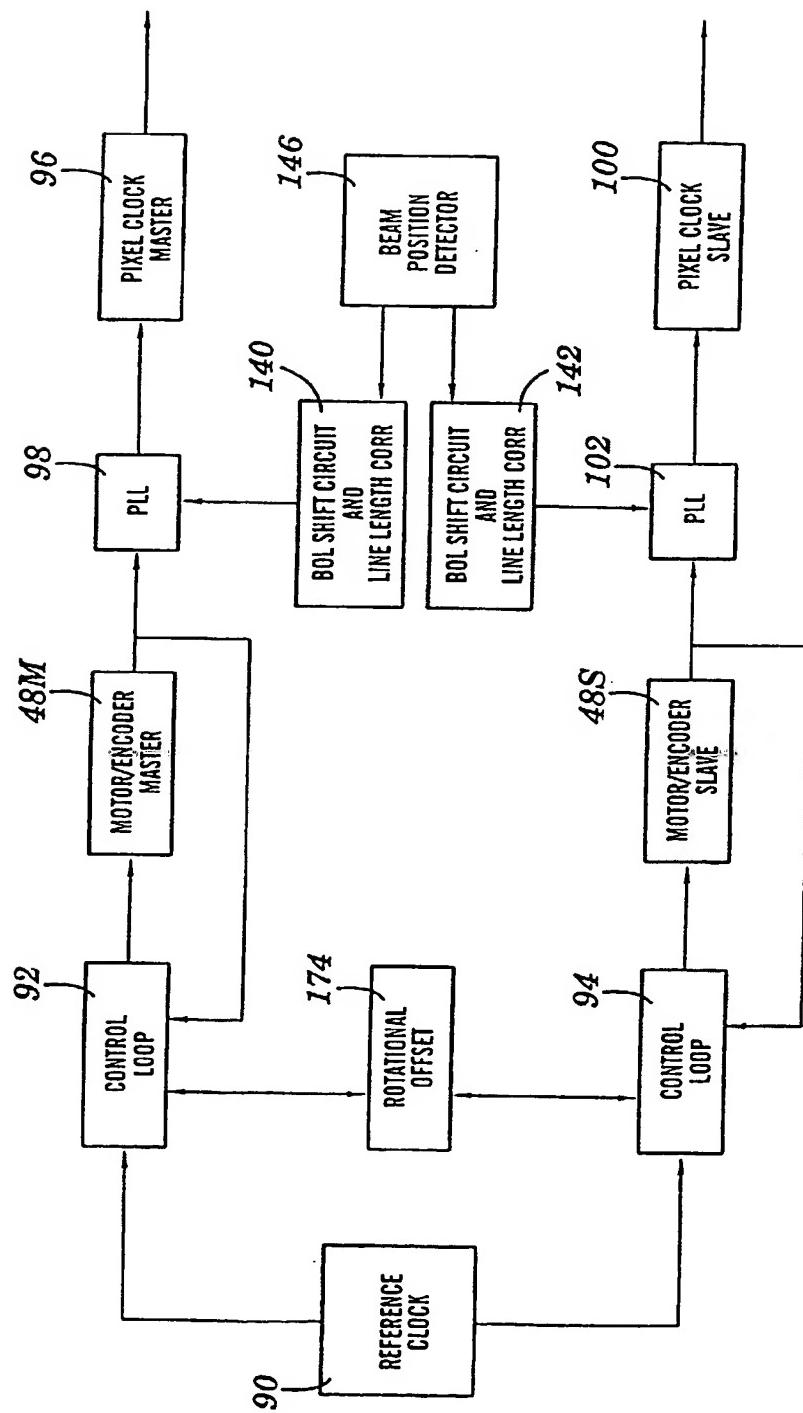


FIG. 6

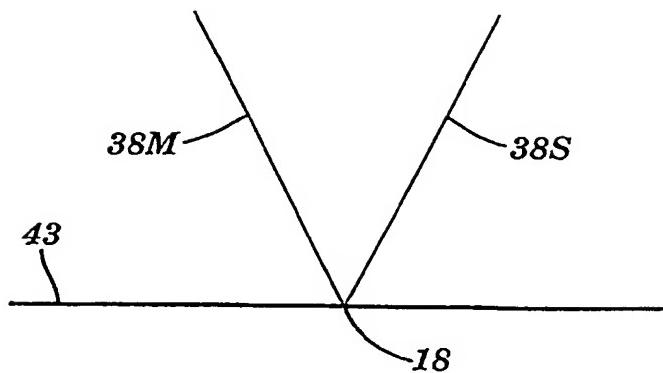


FIG. 7A

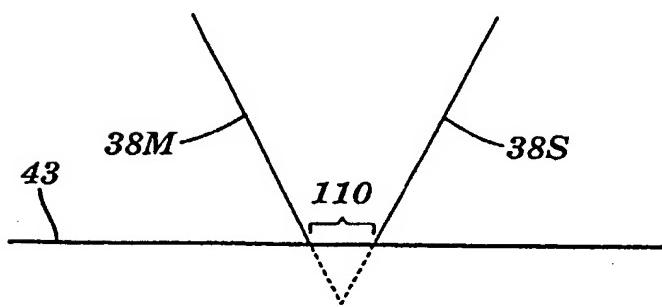


FIG. 7B

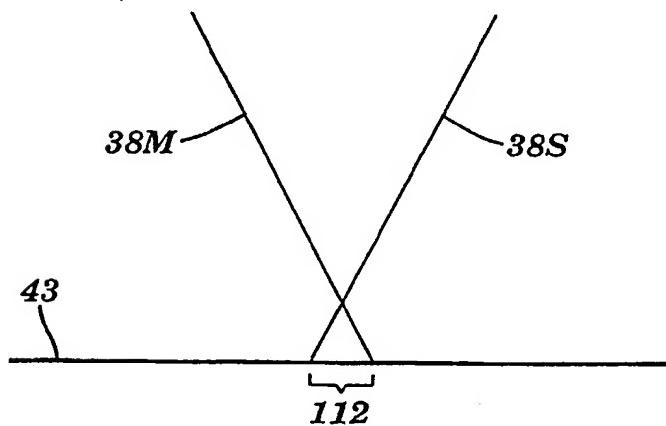


FIG. 7C

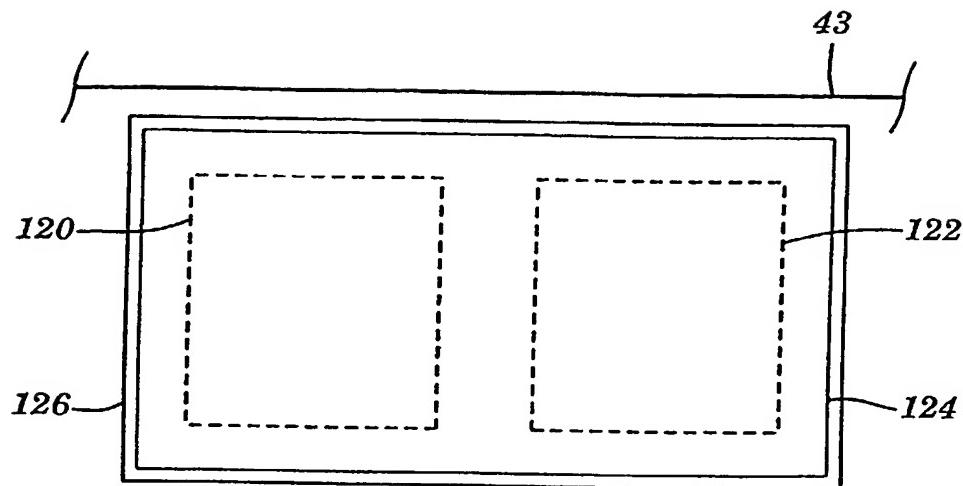


FIG. 8

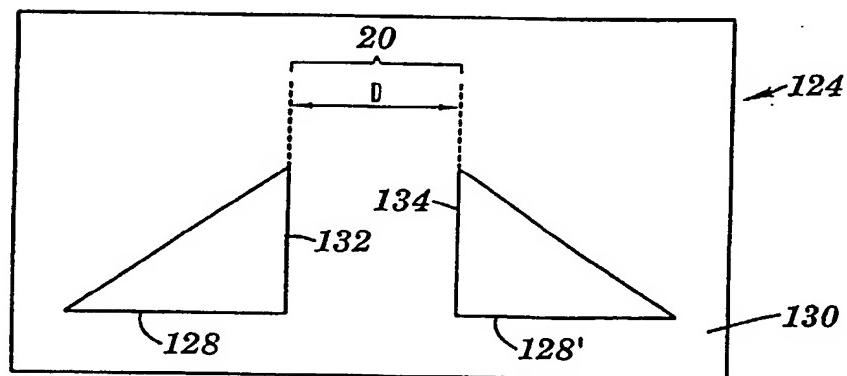
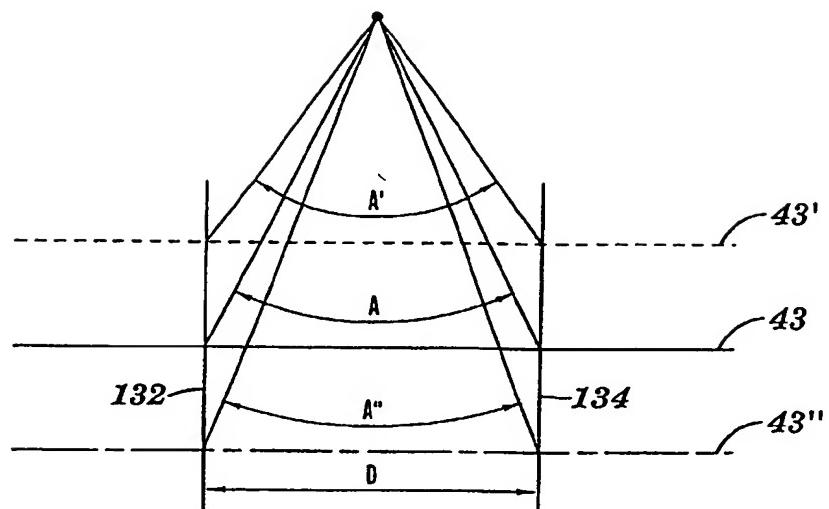
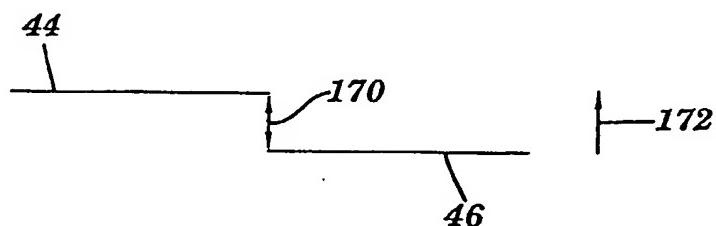
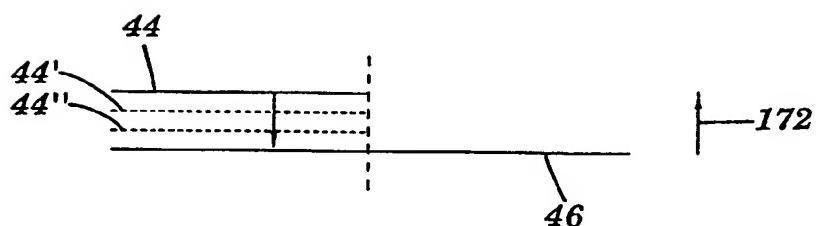


FIG. 9

EP 0 946 043 A2

***FIG. 10******FIG. 11******FIG. 12***

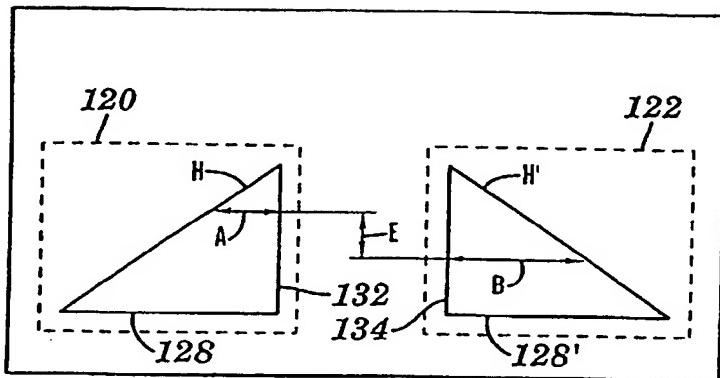


FIG. 13

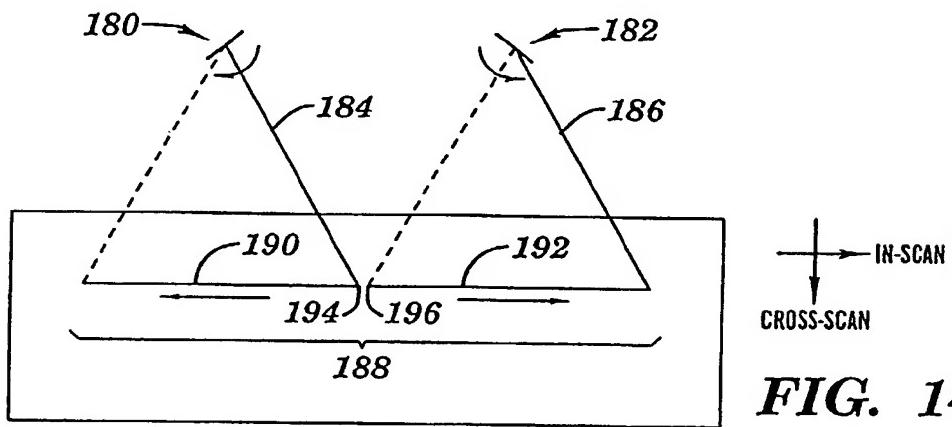


FIG. 14

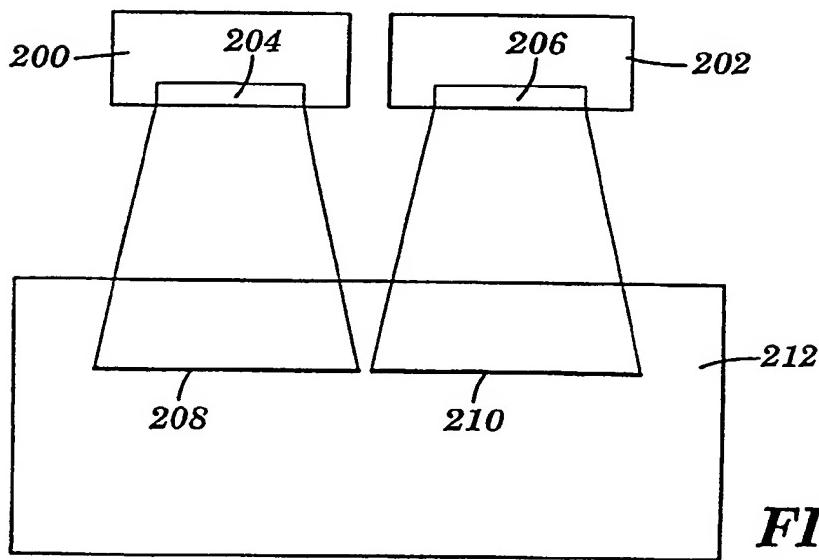


FIG. 15

(19)



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EP 0 946 043 A3

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(54) A method and apparatus for combining a plurality of images without incurring a visible seam

(57) The present invention eliminates artifacts in an image formed using a plurality of imaging sources. Visible seams in the image are eliminated by randomizing the stitch point (18) between the scan lines (44, 46) produced by each imaging source. The randomization may be optimized by additionally applying a method for relocating the random stitch point (18) based on the data content of the scan line, adjacent scan lines, and other

criteria. The present invention further compensates for in-scan and cross-scan errors caused by thermally induced errors, spinner synchronization errors, mechanical misalignment, and other factors associated with the use of a plurality of imaging systems (30). A photodetector system (120, 122, 124), comprising a mask (124) having a pair of triangular openings (128, 128'), provides measurements of the in-scan and cross-scan errors.

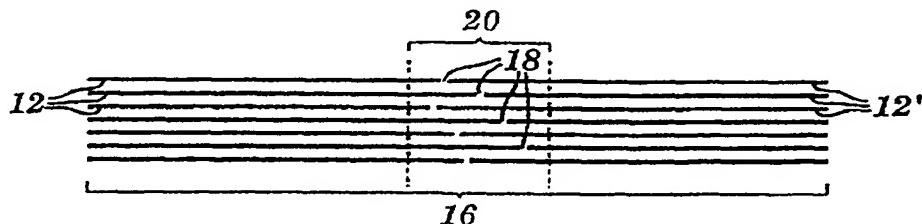


FIG. 2

EP 0 946 043 A3



European Patent
Office

EUROPEAN SEARCH REPORT

Application Number

EP 99 20 0855

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The present search report has been drawn up for all claims			
Place of search		Date of completion of the search	Examiner
BERLIN		4 July 2002	Kassow, H
CATEGORY OF CITED DOCUMENTS			
X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document			
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